

# Predictive Modelling of Formation and Dissolution of Gas Hydrates

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## Reservoir simulation

- Numerical solution of the equations that describe the physical processes of interest on a mesh representing the porous formation (distribution of pressure and temperature, phase saturation, etc.)
- The numerical solutions simulate the behaviour of a real system
- Simulations are widely used for performance analysis and various optimization problems
- Reservoir simulation for hydrate-bearing formations may lead to more effective strategies for methane production and carbon sequestration

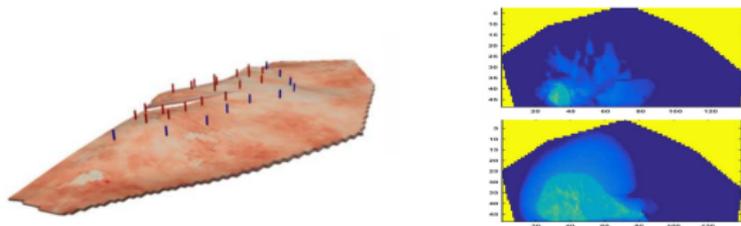


Figure: Kala and Voskov (2018)

# Modelling of gas hydrates

- Review of chemical models for hydrate formation, dissolution and guest molecule exchange
- Implementation into newly developed chemical branch of Delft Advanced Research Terra Simulator (DARTS; <https://darts.citg.tudelft.nl/>)
- Simulation model will be applied to reproduce experimental results produced at UiB (Erslund et al., 2010)
- Predictive model will be constrained to measured data

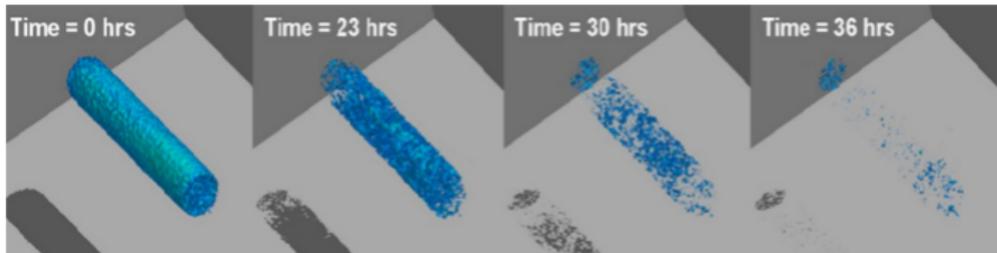


Figure: Hydrate formation. Erslund et al. (2010)

# Modelled processes and assumptions

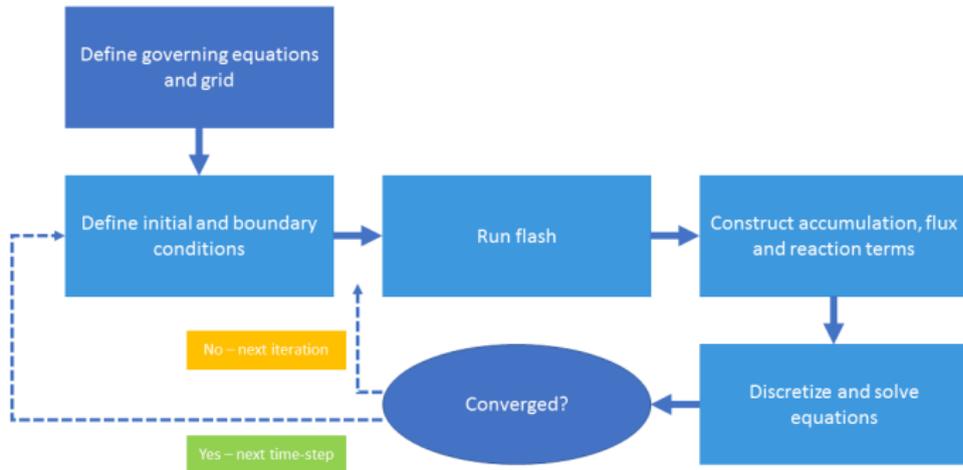
The aim of this project is to model the following processes and phenomena in hydrate-bearing geologic systems:

- The flow of gases and liquids
- The corresponding heat flow and transport
- The formation, dissolution and kinetic exchange of guest molecules of hydrates
  - Kinetic conditions and equilibrium conditions
- Heat exchanges due to advection, conduction, radiation, hydrate reactions and latent heat related to phase changes

Some simplifying assumptions are made:

- Darcy's law is valid in the simulated domain under the conditions of the study
- Instantaneous local thermodynamic equilibrium

# Work flow



## Governing equations

Mass and energy conservation

$$\frac{\partial}{\partial t} \int_{V_n} M^c dV = \int_{\Gamma_n} F^c \cdot \mathbf{n} dA + \int_{V_n} q^c dV$$

where

$$M^c = \phi \rho_T z_c$$

$$F^c = \sum_j (x_{cj} \rho_j \vec{u}_j) = \sum_j (x_{cj} \rho_j \cdot -\frac{k_{r,j} \mathbf{k}}{\mu_j} (\nabla P_j - \rho_j \mathbf{g}))$$

Using the divergence theorem, this reads

$$\frac{\partial}{\partial t} (\phi \rho_T z_c) + \nabla \cdot \left( \sum_j x_{cj} \rho_j \vec{u}_j \right) = \sum_k v_{c,k} r_k \quad c = 1, \dots, n_c \quad (1)$$

$$\frac{\partial}{\partial t} \left( (1 - \phi) \rho_r C_r T + \phi \sum_j \rho_j S_j U_j + Q_{diss} \right) + \nabla \cdot \left( \sum_j h_j \rho_j \vec{u}_j + c \nabla T \right) = 0 \quad (2)$$

## Reaction term

Two types of reactions as proposed by Yonkofski et al. (2016)

- Formation and dissociation:



$$r_k = \begin{cases} K_f \psi_{c,m} A_h (P_{v,m} - P_{eq,h}) & \text{for } P_{v,m} > P_{eq,h} \\ K_d \psi_{c,h} A_h (P_{v,m} - P_{eq,h}) & \text{for } P_{v,m} < P_{eq,h} \end{cases}$$

- Exchange of guest molecules:



$$r_k = K_e f_c A_h (P_{eq,h}^{\text{CH}_4} - P_{v,m}^{\text{CH}_4})$$

where  $K_f$ ,  $K_d$  and  $K_e$  are reaction coefficients (function of composition, pressure and temperature) to be determined

## Discretized equations

After application of a finite-volume discretization and backward Euler approximation in time, the residual form of the 1D mass balance equation (1) reads

$$r_{c,i} = \frac{1}{\Delta t} \left[ (\phi \rho_T z_c)_i^{n+1} - (\phi \rho_T z_c)_i^n \right] - \frac{1}{\Delta x} \left[ (\mathbf{k} f_c)_{i+\frac{1}{2}} [p_{i+1} - p_i] - (\mathbf{k} f_c)_{i-\frac{1}{2}} [p_i - p_{i-1}] \right]^{n+1} - \sum_k v_{c,k} r_k = 0 \quad (3)$$

where fractional flow

$$f_c = \sum_j x_{cj} \rho_j \frac{k_{r,j}}{\mu_j}$$

For a system with  $n_c$  components, this leads to a set of  $n_c - 1$  independent variables for composition and an additional variable for pressure. This yields a total of  $n_c$  equations for each grid block. (Note: to include temperature, add 1 more independent variable)

## Fully implicit method

Backward Euler and secondary variables that are derived from primary variables introduce nonlinearity to the system

$$\rho_T = \rho_T(z_j, p) \quad f_c = f_c(z_j, p) \quad r_k = r_k(z_j, p)$$

To solve this system in a fully implicit manner (that is, all variables simultaneously), we need to converge to a solution of all variables such that all  $n_c$  residuals for each grid block described by (3) are equal to zero using Newton's method. This requires partial derivatives of the residuals with respect to all independent variables:

$$\frac{\partial r_{c,i}}{\partial z_j}, \frac{\partial r_{c,i}}{\partial p} \Rightarrow \frac{\partial \rho_T}{\partial z_j}, \frac{\partial \rho_T}{\partial p}, \dots \Rightarrow \frac{\partial V}{\partial z_j}, \frac{\partial L}{\partial z_j}, \dots$$

## Operator-based linearization

OBL method: introduce operators that capture all nonlinear terms

$$r_{c,i} = \frac{1}{\Delta t} \left[ (\alpha_c)_i^{n+1} - (\alpha_c)_i^n \right] - \frac{1}{\Delta x} \left[ (\mathbf{k}\beta)_{c,i+\frac{1}{2}} [p_{i+1} - p_i] - (\mathbf{k}\beta)_{c,i-\frac{1}{2}} [p_i - p_{i-1}] \right]^{n+1} - \eta_{c,i}^{n+1} = 0$$

where  $\alpha$ ,  $\beta$  and  $\eta$  denote the accumulation, flux and reaction operators, respectively.

- Approximation interpolants for the operators within the parameter space of the simulation problem are stored in  $n_c$ -dimensional tables
- During simulation, operator values are obtained by multilinear interpolation of tabulated values
- Partial derivatives can be evaluated directly from table

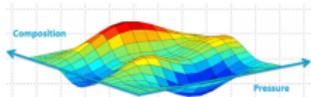


Figure: Operator structure. Voskov (2017)

# Aim

- Include realistic phase behaviour
- Reactions composition-, pressure- and temperature dependent
- Extend to 3D
- Include physical properties (porosity-permeability relationship, etc.) as a function of hydrate saturation
- Implement solution under both kinetic and equilibrium conditions
- Match simulation results to core experiments

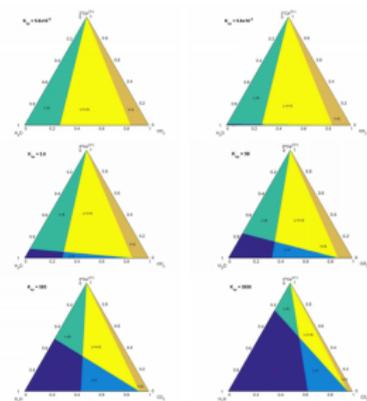


Figure: Phase diagrams used for resolving phase behaviour. Kala and Voskov (2018)

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